

Линейное прибли-е системы в одномерных УГД

$$\frac{\partial \mathcal{L}}{\partial t} + \mathcal{L} \frac{\partial \psi}{\partial x} + \psi \frac{\partial \mathcal{L}}{\partial x} = 0; \quad \frac{\partial \psi}{\partial t} + \psi \frac{\partial \psi}{\partial x} + \frac{1}{\rho} \frac{\partial p}{\partial x} = 0; \quad \text{S-imponere } \frac{\partial \mathcal{L}}{\partial t} + \psi \frac{\partial \mathcal{L}}{\partial x} = 0$$

$P(S,T), S(p,T); p_0, g_0, b \neq 0$; локальные раз с пар-ми $\frac{dS}{db} = 0$

$$p = p_0 + \tilde{p}, \quad g = g_0 + \tilde{g}, \quad v = \tilde{v}; \quad \frac{\partial p}{\partial b} + g \frac{\partial}{\partial k} v + v \frac{\partial}{\partial x} g = 0; \quad \frac{\partial v}{\partial b} + v \frac{\partial v}{\partial k} + \frac{1}{g} \frac{\partial p}{\partial x} = 0$$

$$S = S_0; \frac{\partial S}{\partial x} = 0; S(p, T) \rightarrow T(S, p) \rightarrow T(S, p); p(g, T) \rightarrow p(g, S) \rightarrow p(g, S_0)$$

$$\frac{\partial p}{\partial x} = \frac{\partial}{\partial x} p(y, z) = \frac{\partial p}{\partial y} \cdot \frac{\partial y}{\partial x} + \frac{\partial p}{\partial z} \frac{\partial z}{\partial x} = \frac{\partial p}{\partial y} \bigg|_{z=z_0} \frac{\partial y}{\partial x} = C^2 \frac{\partial p}{\partial x}; \quad \frac{\partial p}{\partial y} \bigg|_{z=z_0} = C^2$$

$$S = S_0 + \tilde{S}, p = p_0 + \tilde{p}, v = \tilde{v} + v_0 = \tilde{v} \Rightarrow \frac{\partial}{\partial t}(S_0 + \tilde{S}) + (S_0 + \tilde{S}) \frac{\partial}{\partial x} \tilde{v} + \tilde{v} \frac{\partial}{\partial x} (S_0 + \tilde{S}) = 0$$

$$\frac{\partial}{\partial t} S_0 + \frac{\partial}{\partial t} S + S \frac{\partial}{\partial x} \tilde{v} + \tilde{S} \frac{\partial}{\partial x} \tilde{v} + \tilde{v} \frac{\partial}{\partial x} S_0 + \tilde{v} \frac{\partial}{\partial x} S = 0$$

$$\frac{\partial}{\partial t} \tilde{\psi} + g_0 \frac{\partial}{\partial x} \tilde{v} = 0; \quad \frac{\partial}{\partial t} \tilde{\zeta} + g_0 \operatorname{div} \tilde{v} = 0$$

$$\frac{\partial v}{\partial t} + v \frac{\partial v}{\partial x} + \frac{1}{\rho} \frac{\partial}{\partial x} \left(\frac{\partial \tilde{v}}{\partial t} + \tilde{v} \frac{\partial v}{\partial x} + G \frac{\partial}{\partial x} (\rho_0 + \tilde{\rho}) \right) = 0$$

$$g_0 \frac{\partial \tilde{r}}{\partial t} + G^2 \frac{\partial}{\partial x} \tilde{g} = 0; \quad g_0 \frac{\partial \tilde{r}}{\partial t} + G^2 v \tilde{g} = 0$$

Ск-ть звука. Ск-ть распр-я палы возм-ти.

1) $\frac{\partial \tilde{p}}{\partial t} + \rho_0 \operatorname{div} \tilde{V} = 0$; $\rho_0 \frac{\partial \tilde{V}}{\partial t} + G^2 \operatorname{grad} \tilde{\zeta} = 0$ (2) (убедимся, что где $\operatorname{div} \tilde{V} = 0$)

$$\frac{\partial}{\partial t}(1) \Rightarrow \frac{\partial^2 \varphi}{\partial t^2} + S_0 \operatorname{div} \frac{\partial \mathbf{v}}{\partial t} = 0 \quad (\text{логично из уравн. no 1 см. (1)}). \text{ Тогда}$$

$$\Rightarrow \int_0 \operatorname{div} \frac{\partial v}{\partial t} + G^2 \operatorname{div}(\operatorname{grad} g) = 0; \int_0 \operatorname{div} \left(\frac{\partial v}{\partial t} \right) + G^2 \Delta g = 0; \frac{\partial g}{\partial t} = 0$$

$$\textcircled{2} \frac{\partial^2 V}{\partial t^2} = G^2 \text{grad div } V; \quad \text{rot rot } V = \text{grad div } V - \Delta V; \quad \text{rot } V = 0 \Rightarrow \text{grad div } V = \Delta V;$$

$$\frac{\partial^2 V}{\partial b^2} = C^2 \Delta U; \quad g \rightarrow p \Rightarrow \frac{\partial^2 p}{\partial b^2} = C^2 \Delta p; \quad \frac{\partial^2 h}{\partial b^2} = C^2 \Delta h, \text{ где } h \leq p, \text{ т.к. } g$$

← гр-е уменьш-то
много

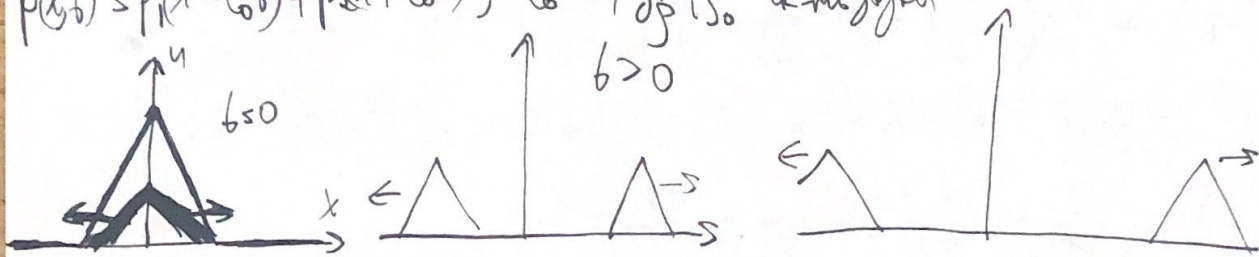
$$u_1(t, 0) = \varphi(t), \quad u_6(t, 0) = \psi(t)$$

$u(x,0) = \varphi(x), \quad u(x,b) = \psi(x)$
 $u(x,b)$ предст. в виде двух член, распр. на $x+b$ и на $x-b$, со ск-тью $\frac{1}{2}$:
 $\frac{1}{2}\varphi(x-b) + \frac{1}{2}\varphi(x+b)$

$$u(x,b) = f_1(x-c_0b) + f_2(x+c_0b); \quad u(x,b) = \frac{\psi(x-c_0b) + \psi(x+c_0b)}{2} + \frac{1}{c_0} \int_{x-c_0b}^{x+c_0b} \psi(z) dz$$

$p(x, b) = g_1(x - c_0 b) + g_2(x + c_0 b)$; $U(x, b) = U_1(x - c_0 b) + U_2(x + c_0 b)$ $\uparrow$ op-ns der Variablen

$$p(x, b) = p_1(x - G_0) + p_2(x + G_0); \quad G_0 = \left. \frac{\partial \varphi}{\partial y} \right|_{y_0} - \text{адиабат. к-ль}$$

[illegible]

$$\frac{P}{g} = \frac{P_0}{g_0} = A = \text{const}; \quad P = Ag; \quad C = \left. \frac{\partial P}{\partial g} \right|_{s=s_0}; \quad P = gRT; \quad \frac{\partial P}{\partial g} = A = P^{1-1} = \frac{P_0}{g_0} \left. \frac{\partial g}{\partial g} \right|_{s=s_0}$$

$$= \frac{P_0}{g_0} g = gRT \Rightarrow \boxed{C^2 = gRT} \quad ; \quad \frac{\partial P}{\partial b} + g \cdot \frac{\partial}{\partial x} v = 0; \quad g = g(x - Cb) + g_2(x + Cb);$$

$$\rho_0 \frac{\partial v}{\partial t} + \rho_0 \frac{\partial^2 \phi}{\partial t^2} = 0; \quad v = v_1(t - \omega b) + v_2(t + \omega b). \text{ Eingesetzt par. } \rho_1(t - \omega b) \text{ u. } v_2(t + \omega b)$$

wegemaltes Bsp-9: $z = t - \cos t \Rightarrow \frac{\partial g}{\partial t} = \frac{dg}{dz} \cdot \frac{dz}{dt} = \frac{dg}{dz} (-\cos t);$

$$\frac{\partial g}{\partial x} = \frac{dg}{dz} \cdot \frac{\partial z}{\partial x} = \frac{dg}{dz} \Rightarrow \begin{cases} g'_1(-\omega) + g_0 v'_1 = 0 \\ g_0(-\omega) v'_1 + \omega^2 g'_1 = 0 \end{cases} \Rightarrow g_0 v'_1 - \omega g'_1 = 0; \quad v_1(z), g_1(z)$$

$$\int_0^1 (g_0 u' - \omega g_1) dz = 0 \Rightarrow g_0 u(1) - \omega g_1(1) \Rightarrow \frac{g_1}{g_0} = \frac{v_1}{\omega} \ll 1;$$

$$g_1 \ll g_0 \Rightarrow \frac{v_1}{\omega} \ll 1, \quad v_1 \ll \omega \quad (\text{ск-мг збукка})$$